Parallel and Distributed Storage

Solutions for the Practice Exercises of Chapter 21

Practice Exercises

21.1

**Answer:**

If there are few tuples in the queried range, then each query can be processed quickly on a single disk. This allows parallel execution of queries with reduced overhead of initiating queries on multiple disks.

On the other hand, if there are many tuples in the queried range, each query takes a long time to execute as there is no parallelism within its execution. Also, some of the disks can become hot spots, further increasing response time.

Hybrid range partitioning, in which small ranges (a few blocks each) are partitioned in a round-robin fashion, provides the benefits of range partitioning without its drawbacks.

21.2

**Answer:**

a. A partitioning vector which gives 5 partitions with 20 tuples in each partition is: [21, 31, 51, 76]. The 5 partitions obtained are 1 – 20, 21 – 30, 31 – 50, 51 – 75, and 76 – 100. The assumption made in arriving at this partitioning vector is that within a histogram range, each value is equally likely.

b. Let the histogram ranges be called $h_1, h_2, \ldots, h_p$, and the partitions $p_1, p_2, \ldots, p_p$. Let the frequencies of the histogram ranges be $n_1, n_2, \ldots, n_p$. Each partition should contain $N/p$ tuples, where $N = \sum_{i=1}^{h} n_i$. 
To construct the load-balanced partitioning vector, we need to determine the value of the $k^1_{th}$ tuple, the value of the $k^2_{th}$ tuple, and so on, where $k_1 = N/p$, $k_2 = 2N/p$, etc., until $k_{p-1}$. The partitioning vector will then be $[k_1, k_2, \ldots, k_{p-1}]$. The value of the $k^i_{th}$ tuple is determined as follows: First determine the histogram range $h_j$ in which it falls. Assuming all values in a range are equally likely, the $k^i_{th}$ value will be

$$s_j + (e_j - s_j) \times \frac{k_{ij}}{n_j}$$

where

- $s_j$ : first value in $h_j$
- $e_j$ : last value in $h_j$
- $k_{ij}$ : $k_i - \Sigma_{i=1}^{j-1} n_i$

### 21.3

**Answer:**

FILL

### 21.4

**Answer:**

a. By replicating across data centers, even if a data center fails, for example due to a power outage or a natural disaster, the data would still be available from another data center. By keeping the data centers geographically separated, the chances of a single natural disaster such as an earthquake or a storm affecting both the data centers at the same time are minimized.

b. Centralized databases typically support only full database replication using log records (although some support logical replication allowing replication to be restricted to some relations). However, they do not support partitioning, or the ability to replicate different parts of the database at different nodes; the latter helps minimize the load increase at a replica when a node fails by spreading the load across multiple nodes

### 21.5

**Answer:**

a. Any updated such as splitting or moving a partition, which is required to balance load, would require a large number of updates to secondary indices.

b. In both cases records may move (across nodes, or to a different location within the node) which would require a large number of updates to sec-
ondary indices if they stored direct pointers. The indirection through the clustering index key / partitioning key allows record movement without any updates to the secondary index.

21.6

Answer:

a. The copies of the data items at a node should be partitioned across multiple other nodes, rather than stored in a single node, for the following reasons:

- To better distribute the work which should have been done by the failed node, among the remaining nodes.
- Even when there is no failure, this technique can to some extent deal with hot-spots created by read-only transactions.

b. RAID level 0 itself stores an extra copy of each data item (mirroring). Thus this is similar to mirroring performed by the database itself, except that the database system does not have to bother about the details of performing the mirroring. It just issues the write to the RAID system, which automatically performs the mirroring.

RAID level 5 is less expensive than mirroring in terms of disk space requirement, but writes are more expensive, and rebuilding a crashed disk is more expensive.

21.7

Answer:

a. Hash partitioning does not permit any control on individual tablet sizes, unlike range partitioning which allows overfull partitions to be split quite easily. B+ tree indices use range partitioning, allowing a leaf node to be split if it is overfull. In contrast, it is not easy to split a hash bucket in a hash index if the bucket is overfull.

Some approaches similar to those used for dynamic hashing (such as linear hashing or extendable hashing) have been proposed to allow overfull hash buckets to be split while leaving other hash buckets untouched, but range partitioning provides a simpler solution.

b. Hashing allows keys of various types to be mapped to a single data type, simplifying the job of partitioning the data. The drawback is that range queries cannot be supported using hashing (without performing a full table scan), whereas direct range-partitioning allows efficient support for range queries.

c. The first option allows reconstruction of records at a single node if a query only accesses records at that node. With the second option, the
vertical fragments corresponding to one record may potentially be residing on different nodes, requiring extra communication to get the vertical fragments together.

21.8

Answer:

a. If a node receives a request for a data item when it is not the master, it can send an error reply with the reason for the error to the requesting node. The requesting node can then find the current master and resend the request to the current master. Alternatively, the old master can forward the message to the new master, which can reply to the requesting node.

b. Tracking mastership on a per-record basis allows the master to be located in a geographical region where most requests for the data item occur, for example the region where the user resides. Reads can then be satisfied without any communication with other regions, which is generally much slower due to speed-of-light delays. Further, writes can also be done locally, and replicated asynchronously to the other replicas.

c. Each record can have an extra hidden field that stores the master replica of that record. In case the information is outdated, all the replicas of the data item can be accessed to find the nodes listed as masters for that data item; those nodes can be contacted to find the current master.